

ABSTRACT

A steering booster process is provided for a motor vehicle with a steering arrangement for the input of a set steering variable by a driver, several travel sensors for detecting travel dynamic variables, a steering control system by way of which a steering control variable, which is determined dependent on the output variables of the several travel sensors, is overlapped on the set steering variable, as well as at least one other control system that influences the performance of the motor vehicle, which evaluates data from the steering control system. The additional control system is especially a braking control system for stabilizing the vehicle stability by braking individual vehicle wheels. The additional control system evaluates the set steering variable overlapped by the steering control variable from the steering control system.